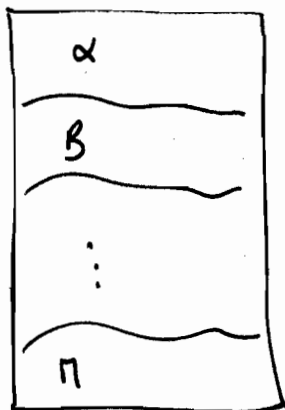


PHASE EQUILIBRIUM + STABILITY (15)

Goal of this Chapter: General Relationships valid for systems at phase coexistence.

Phase Rule



Phases $\alpha, \beta, \dots, \pi$ @ coexistence.

Each phase can be characterized by $n+1$ intensive variables -
Let's choose

$$T, P, x_1, \dots, x_{n-1}$$

n is # of components

total
=
 $(n+1) \times \pi$

For equilibrium,

$$T^\alpha = T^\beta = \dots = T^\pi$$

$$P^\alpha = P^\beta = \dots = P^\pi$$

$$m_1^\alpha = m_2^\beta = \dots = m_1^\pi$$

\vdots

$$m_n^\alpha = m_n^\beta = \dots = m_n^\pi$$

$(\pi-1) \times (n+2)$
equations

Number of "degrees of freedom" -

$$\begin{aligned} \text{Variables} - \text{equations} &= (n+1) \times \pi - (\pi-1) \times (n+2) = \\ &= n\pi + \pi - n\pi - 2\pi + n + 2 = \underline{\underline{n - \pi + 2}} \end{aligned}$$

Differential Approach (§ 15.2 - Review Phase Diagrams on your own)

In the book, the relationships below are derived using fugacities. Here, I use chemical potentials.

The two approaches are equivalent, since

$$\mu_i = RT \ln \hat{f}_i + \text{a function of } T \text{ only}$$

Consider a binary system with components 1 and 2.

Two phases, α and β .

Must have:

$$\left. \begin{aligned} T^\alpha &= T^\beta \\ P^\alpha &= P^\beta \\ \mu_1^\alpha &= \mu_1^\beta \\ \mu_2^\alpha &= \mu_2^\beta \end{aligned} \right\} \begin{array}{l} \text{Functions of } T, P \\ \text{and } x_1^\alpha, x_1^\beta \end{array}$$

Consider a change in T , P or x_1 while the system remains at equilibrium with phases α and β present.

$$\begin{aligned} d\mu_1^\alpha &= d\mu_1^\beta \Rightarrow \\ \left(\frac{\partial \mu_1^\alpha}{\partial T} \right)_{P, x_1^\alpha} dT + \left(\frac{\partial \mu_1^\alpha}{\partial P} \right)_{T, x_1^\alpha} dP + \left(\frac{\partial \mu_1^\alpha}{\partial x_1^\alpha} \right)_{T, P} dx_1^\alpha &= \\ = \left(\frac{\partial \mu_1^\beta}{\partial T} \right)_{P, x_1^\beta} dT + \left(\frac{\partial \mu_1^\beta}{\partial P} \right)_{T, x_1^\beta} dP + \left(\frac{\partial \mu_1^\beta}{\partial x_1^\beta} \right)_{T, P} dx_1^\beta & \\ \left(\frac{\partial \mu_1^\alpha}{\partial T} \right)_{P, x_1^\alpha} = -\bar{S}_1^\alpha = -\frac{\bar{H}_1^\alpha - \mu_1^\alpha}{T} \quad \left(\frac{\partial \mu_1^\alpha}{\partial P} \right)_{T, x_1^\alpha} = \bar{V}_1^\alpha & \end{aligned}$$

Substituting expressions for the derivatives:

$$\textcircled{1} \left[- \frac{(\bar{H}_1^\alpha - \bar{H}_1^\beta) - (\bar{H}_1^\beta - \bar{H}_1^\beta)}{T} dT + (\bar{V}_1^\alpha - \bar{V}_1^\beta) dP + \left(\frac{\partial \bar{H}_1^\alpha}{\partial x_1^\alpha} \right)_{T,P} dx_1^\alpha - \left(\frac{\partial \bar{H}_1^\beta}{\partial x_1^\beta} \right)_{T,P} dx_1^\beta = \phi \right]$$

Similarly, starting from $d\mu_2^\alpha = d\mu_2^\beta$, we obtain

$$\textcircled{2} \left[- \frac{\bar{H}_2^\alpha - \bar{H}_2^\beta}{T} dT + (\bar{V}_2^\alpha - \bar{V}_2^\beta) dP + \left(\frac{\partial \bar{H}_2^\alpha}{\partial x_1^\alpha} \right)_{T,P} dx_1^\alpha - \left(\frac{\partial \bar{H}_2^\beta}{\partial x_1^\beta} \right)_{T,P} dx_1^\beta = \phi \right]$$

In $\textcircled{1}$ and $\textcircled{2}$, we have dP , dT , dx_1^α and dx_1^β as unknowns. We can eliminate dx_1^α (or dx_1^β) from the Gibbs-Duhem relationship:

$$N_1 d\mu_1 + N_2 d\mu_2 = \phi \Rightarrow x_1 d\mu_1 + x_2 d\mu_2 = \phi \Rightarrow$$

$$\Rightarrow x_1^\alpha \left(\frac{\partial \bar{H}_1^\alpha}{\partial x_1^\alpha} \right)_{T,P} dx_1^\alpha + x_2^\alpha \left(\frac{\partial \bar{H}_2^\alpha}{\partial x_1^\alpha} \right)_{T,P} dx_1^\alpha = \phi \quad \textcircled{3}$$

$$\textcircled{1} \cdot x_1^\alpha + \textcircled{2} \cdot x_2^\alpha \quad \textcircled{3} \quad - \frac{x_1^\alpha (\bar{H}_1^\alpha - \bar{H}_1^\beta) + x_2^\alpha (\bar{H}_2^\alpha - \bar{H}_2^\beta)}{T} dT + \left[x_1^\alpha (\bar{V}_1^\alpha - \bar{V}_1^\beta) + x_2^\alpha (\bar{V}_2^\alpha - \bar{V}_2^\beta) \right] dP - \left[\left(x_1^\alpha - x_2^\alpha \frac{x_1^\beta}{x_2^\beta} \right) \left(\frac{\partial \bar{H}_1^\beta}{\partial x_1^\beta} \right)_{T,P} \right] dx_1^\beta = \phi$$

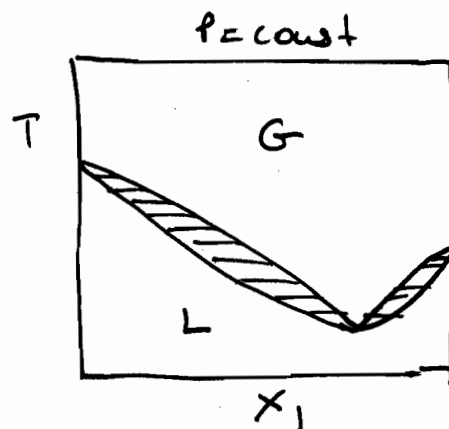
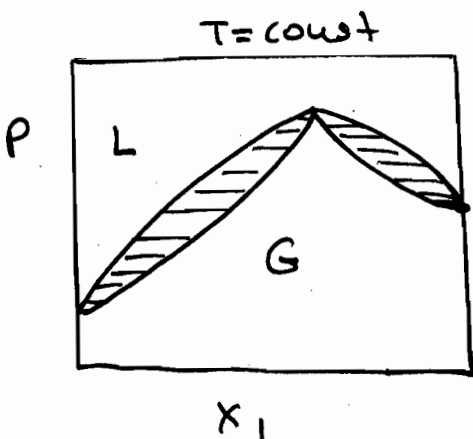
This relationship links dT , dP and dx_1^β at α - β coexistence. In its simplest form, you have seen this as the "Clausius-Clapeyron" Equation for a one-component system.

For example:

$$\left(\frac{dP}{dT}\right)_{x_1^B, [\alpha-B \text{ coex}]} = \frac{x_1^\alpha (\bar{H}_1^\alpha - \bar{H}_1^B) + x_2^\alpha (\bar{H}_2^\alpha - \bar{H}_2^B)}{T [x_1^\alpha (\bar{V}_1^\alpha - \bar{V}_1^B) + x_2^\alpha (\bar{V}_2^\alpha - \bar{V}_2^B)]} \quad (1)$$

$$\left(\frac{\partial P}{\partial x_1^B}\right)_T, [\alpha-B \text{ coex}] = \frac{\left(x_1^\alpha - x_2^\alpha \frac{x_1^B}{x_2^B}\right) \left(\frac{\partial H_1^B}{\partial x_1^B}\right)}{x_1^\alpha (\bar{V}_1^\alpha - \bar{V}_1^B) + x_2^\alpha (\bar{V}_2^\alpha - \bar{V}_2^B)} \quad (2)$$

Exercise: Prove that fig. 15.1 is wrong!

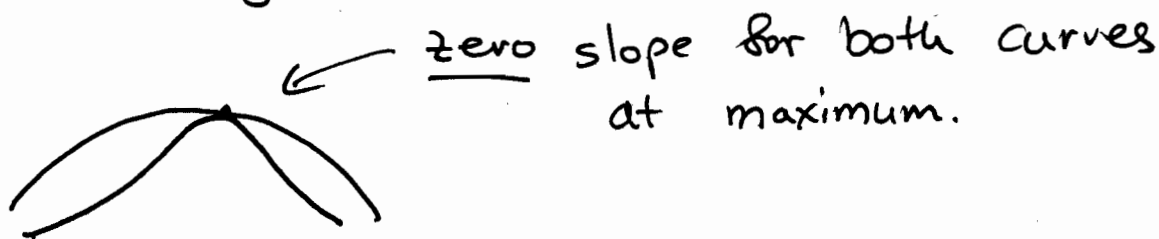


For an azeotrope, $x_1^\alpha = x_1^B \Rightarrow x_2^\alpha = x_2^B$

From (2) above, $\left(\frac{dP}{dx_1^B}\right)_{T, [\alpha-B]} = \phi = \left(\frac{\partial P}{\partial x_1^\alpha}\right)_{T, \text{ azeotr. } [\alpha-B]}$

Similarly, $\left(\frac{\partial T}{\partial x_1^\alpha}\right)_{T, [\alpha-B \text{ coex}]} = \phi = \left(\frac{\partial T}{\partial x_1^B}\right)_{T, \text{ azeotr.}}$

Correct figure:



Simplification for 1-component systems

Equation (1) on the previous page is simplified for one-component systems:

$$\left(\frac{dP}{dT}\right)_{\alpha-B \text{ coex}} = \frac{H^\alpha - H^\beta}{T(V^\alpha - V^\beta)} = \frac{\Delta H^{\alpha\beta}}{T\Delta V^{\alpha\beta}}$$

In the case $\alpha = \text{vapor}$ $\beta = \text{liquid}$, further simplifications are possible. $\Delta V^{\alpha\beta} = V^{\text{vapor}} - V^{\text{liquid}} \approx$

$$V^{\text{vapor}} \approx \frac{RT}{P} \Rightarrow \left(\frac{dP}{dT}\right)_{VL} = \frac{P\Delta H^{\text{vap}}}{RT^2} \Rightarrow$$

$$\frac{d(\ln P)}{d(1/T)} = -\frac{\Delta H^{\text{vap}}}{R} \quad \left. \vphantom{\frac{d(\ln P)}{d(1/T)}} \right\} \text{Clausius-Clapeyron}$$

For solid-liquid equilibria, $\left(\frac{dP}{dT}\right)_{S-L} = \frac{\Delta H^{\text{melt}}}{T\Delta V^{\text{melt}}}$

$$H^{\text{LIQ}} - H^{\text{SOLID}} > 0 \Rightarrow \left(\frac{\partial P}{\partial T}\right)_{S-L} > 0 \quad \text{if } V^{\text{LIQ}} > V^{\text{SOLID}}$$

$$\left(\frac{\partial P}{\partial T}\right) < 0 \quad \text{if } V^{\text{LIQ}} < V^{\text{SOLID}} \quad (\text{e.g. for water})$$

